STRESS ANALYSIS IN WELDED BUTT JOINTS

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In this study a symmetric contact problem of strips containing in this study a symmetric contact problem of surps containing cracks is considered. Three strips are perfectly bonded over a finite length and are assumed to be isotropic. Uniaxial tension is applied to the middle strip away from the contact region. is applied to the illiquie surp away from the contact region.

Integral transforms are used to reduce the problem to a system integral transforms are used to reduce the problem to a system of singular integral equations of the second kind. The contact stresses and corresponding stress intensity factors are evaluated and presented for various strip geometries and material combinations.

INTRODUCTION

Within the past two decades, problems of bonded dissimilar materials and load within the past two decades, problems of bonded dissimilar materials and load transfer problems in strips have attracted considerable attention. Since many engineering structures are comprised of more than one elastic material, the fracture at the interface between dissimilar material can be a critical phenomena in engineering structures are comprised of more than one elastic material, the fracture at the interface between dissimilar material can be a critical phenomenon in many structures. For example, in [1] Keer analyzed the problem of a line bond between two layers. In this study, although the problem is formulated for dissimilar layers, numerical results are given only for the case of identical layers. In another study Yahşi and Göçmen [2] considered a finite contact problem for two perfectly study Yahşi and Göçmen [2] considered bonded dissimilar infinite strips. In this study both of the strips are assumed to be study Tanşı and Ooçmen [2] considered a finite contact problem for two perfectly bonded dissimilar infinite strips. In this study both of the strips are assumed to be isotropic and uniaxial tension is applied to the lower strip away from the contact stresses that they obtained had a source root region. However, the contact stresses that they obtained had a square root region. However, the contact stresses that they obtained had a square root singularity without oscillation at the edge of the bond region; their solution therefore appropriate only for identical materials. The same problem was reconsidered by Keer and Guo [3] and a system of singular integral equations of the second kind are obtained for the contact stresses, thereby yielding an oscillatory stress field near the Keer and Guo [3] and a system of singular integral equations of the second kind are obtained for the contact stresses, thereby yielding an oscillatory stress field near the crack tip. In a recent paper by Yahşi and Yazıcı [4] the contact problem for two bonded dissimilar homogeneous elastic strips is considered. In this study, the lower

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strip was assumed to have two symmetric cracks perpendicular to the interface and subject to uniform tensile stresses far from the contact zone.

In this study, three symmetric isotropic strips are considered. Three strips are assumed to be perfectly bonded to each other through a finite length as shown in Fig. 1. The middle strip containing a pair of symmetric cracks is subjected to a uniform tensile stress far from the interface.

To solve the problem, the stress and displacement fields of an elastic infinite strip are obtained from the plane elasticity equations for an isotropic material by using Fourier transform techniques and a crack solution and a constant uniform stress solution is added to the middle strip solution. Finally, by using the appropriate boundary conditions the problem is reduced to a system of singular integral equations of the second kind.

FORMULATION OF THE PROBLEM

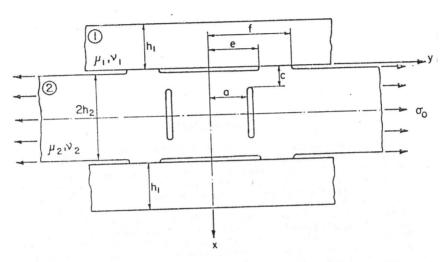


Figure 1 Geometry of perfectly bonded infinite strips.

Consider a strip of thickness $2h_2$ and elastic constants μ_2 , κ_2 bonded to two infinite strips of elastic constants μ_1 , κ_1 (Fig. 1), where $\kappa_j = 3\text{-4}\ \upsilon_j$ for plane strain and $\kappa_j = (3\text{-}\upsilon_j)\ /\ (1\text{+}\upsilon_j)$ for generalized plane stress, υ_j (j=1,2) being the Poisson's ratio. Thus, $\kappa_j = k_2$ is a plane of symmetry and the boundary and continuity conditions may be expressed as

$$\sigma_{xx}^{(1)}(-h_1, y) = \sigma_{xy}^{(1)}(-h_1, y) = 0, \quad -\infty < y < \infty$$
(2a,b)

$$\sigma_{xx}(-n_1, y) = \sigma_{xy}(-n_2, y) = \sigma_{xx}(0, y) = G_1(y), \quad -\infty < y < \infty$$
(2a,b)

$$\sigma_{xx}(0,y) = \sigma_{xx}(0,y) = \sigma_{xy}(0,y) = G_2(y), \quad -\infty < y < \infty$$
(3a,b)

$$\sigma_{xy}(0,y) = \sigma_{xy}(0,y)$$

$$\sigma_{xy}(h_2,y) = 0, \quad u^{(2)}(h_2,y) = 0, \quad -\infty < y < \infty$$
(4a,b)

$$\frac{\partial r_{i}^{(1)}(0,y)}{\partial y} = \frac{\partial r_{i}^{(2)}(0,y)}{\partial y} , \quad e \le |y| \le f, \quad i=1,2, \quad r_{1} = u, \quad r_{2} = v$$
(5a,b)
(6a,b)

$$\frac{\partial y}{\partial x_j} \frac{\partial y}{(x, \pm a) = 0} ; j = x, y; c < x < d$$

$$(6a,b)$$

$$G_{xj}(x, \pm a) = 0$$
, $(i = 1,2)$, $|y| < e$ or $|y| > f$ (7)
where $G_i(y) = 0$, $(i = 1,2)$, $|y| < e$ or $|y| > f$ and (2)

In (1-6) and for the remainder of this section the superscripts (1) and (2) refer to the upper and middle strips, respectively.

Using the expressions given in [5] for an infinite plane for a pair of point dislocations with densities f_1 and f_2 located at the point (x_0, y_0) and defined by

tions with densities
$$I_1$$
 and I_2 .

$$\frac{\partial}{\partial x} [r_i^{(1)}(x_0, 0) - r_i^{(2)}(x_0, 0)] = f_i(x_0) \delta(x - x_0), i = 1, 2, r_1 = v, r_2 = u$$
(8a,b)

and standard Fourier transforms, the displacement and stress fields for the upper and lower strips can easily be obtained as given in [5].

Instead of dislocations if the middle strip contains cracks along c < x < d, $y_0 = \pm a = \text{constant}$, as shown in Figure 1, under a given set of surface tractions as $y_0 = \pm a = \text{constant}$, as snown in Figure 1, under a given set of surface tractions as stated in the equations (6a,b), by integrating the solution found for dislocations one would obtain the solution for the cracks.

By using the stress and displacement equations for the middle and upper strips given in [5] and the boundary conditions (1-4) and equations (7) and (8a,b) strips given in [5] and the boundary conditions (1-4) and equations (7) and (8a,b) all the unknowns of the problem can be expressed in terms of $f_i(x)$, $G_i(y)$, (i=1,2). Thus the complete solution of the problem is obtained once the unknown functions. Thus the complete solution of the problem is obtained once the unknown functions f_1 , f_2 , G_1 , and G_2 , are determined. Finally, by substituting the stress and displacement expressions obtained in terms of $f_i(x)$, $G_i(y)$, (i=1,2), into the continuity conditions (5a,b) and the crack surface boundary conditions (6a,b) one upould obtain the system of four singular integral equations given in [5] to would obtain the system of four singular integral equations given in [5] to determine the functions $f_i(x)$ and $G_i(y)$, (i=1,2).

By extending the cracks to the upper and lower boundaries of the middle strip (i.e. c = 0, $d = h_2$) the problem can be reduced to a butt joint under the effect of uniform stresses. For this case by introducing the following substitutions into singular integral equations given in [5],

$$x = 0.5 h_2 (1 + \tau)$$
, $-1 < \tau < +1$, (9a)

$$t_2 = 0.5 h_2 (1 + \rho)$$
, $-1 < \rho < 1$, (9b)

$$t_1 = 0.5 (f + e) + 0.5 (f - e) \xi$$
, $-1 < \xi < 1$, (9c)

$$y = 0.5 (f + e) + 0.5 (f - e) \eta$$
, $-1 < \eta < 1$, (9d)

$$\phi(\xi) = G_2(\xi) + iG_1(\xi)$$
, $\psi(\tau) = f_1(\tau) + if_2(\tau)$, $i = \sqrt{-1}$, (10a,b)

these singular integral equations are reduced into the following form:

$$\begin{split} \gamma\phi(\eta) + \frac{1}{\pi i} \int_{-1}^{+1} \frac{\phi(\xi)}{\xi - \eta} \, d\xi + \int_{-1}^{+1} \left\{ \psi(\rho) \, K_{11}(\rho, \eta) + \frac{-}{\psi(\rho)} \, K_{12}(\rho, \eta) \right\} \, d\rho \\ + \int_{-1}^{+1} \left\{ \phi(\xi) \, K_{13}(\xi, \eta) + \frac{-}{\phi(\xi)} \, K_{14}(\xi, \eta) \right\} \, d\xi = h_1(\eta) \,, \quad -1 < \eta < 1 \;, \end{split} \tag{11a}$$

$$\begin{split} &\int_{-1}^{+1} \psi(\rho) \; K_{2S}(\rho,\tau) \, d\rho + \int_{-1}^{+1} \left\{ \psi(\rho) \; K_{21}(\rho,\tau) + \overline{\psi(\rho)} \; K_{22}(\rho,\tau) \right\} \, d\rho \\ &\quad + \int_{-1}^{+1} \left\{ \phi(\xi) \; K_{23}(\xi,\tau) + \overline{\phi(\xi)} \; K_{24}(\xi,\tau) \right\} \, d\xi = h_2(\tau) \; , \; -1 < \tau < 1 \; , \end{split} \tag{11b}$$

where the expressions of kernels K_{ij} (i=1,2, j=S, 1,2,3,4) and known functions $h_1(\eta)$ and $h_2(\tau)$ are given in [5].

NUMERICAL RESULTS AND DISCUSSION

The singular integral equations (11a,b) can be solved with the conditions

$$\psi(\pm 1) = 0$$
, $\int_{-1}^{1} \phi(\xi) d\xi = 2 \frac{p+Q}{f-e}$ (12a,b,c)

by using the method given in [5], where the solution of equations (11a,b) are approximated by

where
$$\alpha_1 = \frac{1}{2} - i\omega$$
, $\beta_1 = -\frac{1}{2} + i\omega$, $\alpha_2 = \beta_2 = -\frac{1}{2}$, $\omega = \frac{1}{2\pi} \log \left(\frac{1+\gamma}{1-\gamma} \right)$ (14a,d)

and the unknown functions $F(\eta)$ and $R(\tau)$ are approximated by a series expansion of orthogonal polynomials with unknown coefficients.

By using the following definition of stress intensity factor

By using the following
$$k_1(e) - ik_2(e) = \lim_{t \to e} (t - f)^{-\alpha_1} (e - t)^{-\beta_1} (G_1 - iG_2) \tag{15}$$

and equation (13a) the normalized stress intensity factors can be obtained as follows:

quation (13a) and
$$v_{s}$$
:
$$k_{1}(e) - ik_{2}(e) = \frac{i}{2} \frac{F(-1)}{\sigma_{o}}, \quad k_{1}(f) - ik_{2}(f) = \frac{i}{2} \frac{F(+1)}{\sigma_{o}}$$
(16a,b)
$$\frac{1}{\sigma_{o}} = \frac{i}{\sigma_{o}} + \frac{F(-1)}{\sigma_{o}}$$
(16a,b)

Figures 2-5 give the first and second mode stress intensity factors, k₁ and k₂, versus e/h₁, respectively, for different material combinations of aluminium and stress. In the numerical calculations for plane strain, the following material constants are used are used.

aluminium :
$$\mu_a = 26.32$$
 GPa, $\nu_a = 0.33$
steel : $\mu_s = 80.77$ GPa, $\nu_s = 0.3$

From these figures, it is seen that at y=e, first mode stress intensity factor increases with the increase of e/h₁ ratio at y=f which is the closest and to the decreasing with the increase of e/h₂ ratio at y=f which is the closest and to the decreases with the increase of e/h₁ ratio. On the other hand, as expected, it is decreasing with the increase of e/h₁ ratio at y=f which is the closest end to the applied tensile stress. In general, first mode stress intensity factors decreases as the contact length increases

It is also found that the material dependence of k2 is much more stronger contact length increases. thanofk₁, and second mode stress intensity factor increase with the increase in contact length.

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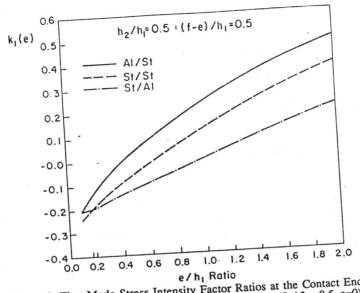


Figure 2. First Mode Stress Intensity Factor Ratios at the Contact End (y=e) of Perfectly Bonded Infinite Symmetric Strips (h₂/h₁=0.5, (f-e)/h₁=0.5, c=0).

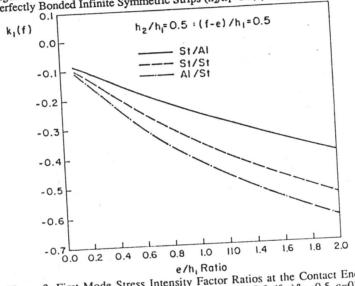


Figure 3. First Mode Stress Intensity Factor Ratios at the Contact End (y=f) of Perfectly Bonded Infinite Symmetric Strips $(h_2/h_1=0.5, (f-e)/h_1=0.5, c=0)$.

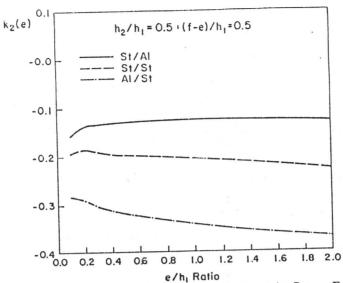


Figure 4. Second Mode Stress Intensity Factor Ratios at the Contact End (y=e) of Perfectly Bonded Infinite Symmetric Strips (h₂/h₁=0.5, (f-e)/h₁=0.5, c=0).

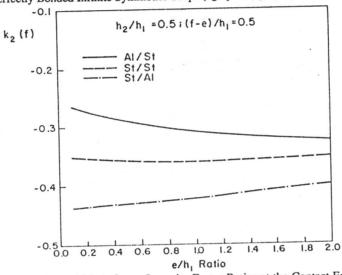


Figure 5. Second Mode Stress Intensity Factor Ratios at the Contact End (y=f) of Perfectly Bonded Infinite Symmetric Strips ($h_2/h_1=0.5$, (f-e)/ $h_1=0.5$, c=0).